Chaos Communication System using MIMO Technique

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Abstract— The security of chaos communication system is superior to other digital communication system, because it has characteristics such as non-periodic, wide-band, nonpredictability, easy implementation and sensitive initial condition. However, chaos communication system increases the number of transmitted symbols by spreading and transmitting information bits according to characteristic of chaos maps. So the research that improves data transmission speed is necessary for chaos communication system. If many antennas are applied to chaos communication system, the capacity of data is proportional to the number of antenna.so it is good way applying multiple-input and multiple-output (MIMO) to the chaos communication system. In this paper, we propose the correlation delay shift keying (CDSK) using 2×2 MIMO technique and evaluate BER performance over Rayleigh MIMO fading channel. Lastly we evaluate BER performance applying the boss map with 2x2 MIMO using MIMO detection algorithm such as zero forcing (ZF) and minimum mean square error (MMSE).

Keywords— Chaos Communication System; CDSK; MIMO; Zero Forcing; MMSE;

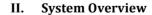
I. Introduction

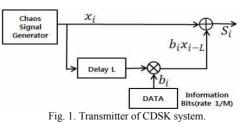
Previous digital communication technology continually used a linear system. However, as this technology reached basic limit, people started to improve performance of nonlinear communication systems applying chaos communication systems to nonlinear systems [1]. Chaos communication systems have the characteristics such as nonnon-predictability wide-band, and periodic easy implementation. Also, chaos communication system is decided by initial conditions of equation, and it has sensitive characteristic according to initial condition, because chaos signal is changed to different signal when initial condition is changed [2-3]. Chaos signal is expressed as randomly and non-linearly generated signal, but it is possible to predict in principle. And it is possible to determine value of the future by value of the past. So, if initial conditions of chaos signal is not exact, users of chaos system are impossible to predict the value of chaos signal because chaos signal has sensitive characteristic about initial conditions [1][4]. As these characteristics, the security of chaos communication system is superior to digital communication system.

Due to security and advantage, chaos communication system are being studied continuously. Look at existing research, in order to solve disadvantage that bit error rate (BER) performance of this system is bad, chaos communication system is evaluated the BER performance according to chaos maps, and find a chaos map that has the best BER performance [5]. In addition, chaos users evaluate the BER performance according to chaos modulation system [6-7], and propose a new chaos map that has the best BER performance according to analysis of probability density function[8]. Also, studies about security and anti-jamming of chaos communication system was studied [9-10].

Chaos communication system has many transmitted symbols, because information signal is spread according to the characteristic of chaos map. So, study of chaos system for data rate improvement is necessary. MIMO(Multi Input Multi Output) system transmit data by several paths using several antennas. And, in receiver part, it is a technique which can reduce interference by detecting received signal at each path, and make better each data rate. MIMO system increase the capacity of data communication in proportion to number of antenna, and provide the high data processing Speed[11-12]. Therefore, study that MIMO system is applied to chaos communication system is important. MIMO detection algorithm is necessary in receiver part when MIMO system is used because signal that transmit from different antenna is added to desired signal. Also, each MIMO detection algorithm is necessary to evaluate and find MIMO detection algorithm that has good performance, because BER performance is different according to MIMO detection algorithm

In this paper, in Rayleigh fading channel, BER performances of CDSK system that is applied 2x2 MIMO with Zero Forcing and MMSE evaluate. Also, BER performances of CDSK system that is applied 2x2 MIMO with MIMO detection algorithm is evaluated, and we compare BER performance of Zero Forcing and MMSE. At existing study, we proposed a novel chaos map in order to improve the BER performance[8], and we named a novel chaos map "Boss map". And we evaluate the performance of Zero Forcing and MMSE when 2x2 MIMO is applied to CDSK using Boss map.





A. Correlation Delay Shift Keying system

CDSK system has a adder in transmitter. Existing modulation system than CDSK system consists switch in transmitter, and problem of power waste and eavesdropping occurs by twice transmission. Technique that has been proposed for these problems solution is CDSK system. And, transmitted signal does not repeat by replacing an adder with a switch in the transmitter.

Figure 1 shows transmitter of CDSK system. CDSK transmitter is composed of sum that is added delay chaos signal multiplied information bit and generated chaos signal from chaos signal generator. Also, M means spreading factor, and information bit that is spread as much as spreading factor is multiplied by delay chaos signal.

$$S_i = x_i + b_i x_{i-L} \tag{1}$$

Equation(1) indicates transmitted signal from transmitter. Also, L means delay time, and this equation is expressed as sum that is added delay chaos signal multiplied information bit and generated chaos signal.

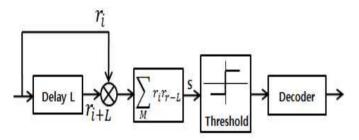


Fig. 2. Receiver of CDSK system.

Figure 2 shows receiver of CDSK system. CDSK receiver is correlator based receiver, and it is performed in order to recover the symbol. Received signal and delay received signal are multiplied, and this signal is as much added as spreading factor. Afterward the signal pass through the threshold, and information signal recover through decoding.

$$S = \sum_{i=1}^{M} r_{i} r_{i-L}$$
(2)

Equation(2) indicates output value of correlator of CDSK system. At this time, information bits is possible to recover when delay time(L) and spreading factor(M) have to use exact value that is used in transmitted signal.

B. Chaos map

In this paper, types of chaos map are used Tent map and Boss map. At existing study, Boss map means a novel chaos that we proposed for BER performance improvement[8].

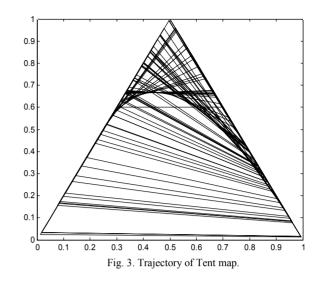


Figure 3 shows trajectory of Tent map. The x-axis and the y-axis of figure 3 mean x_n and x_{n+1} , and Tent map has trajectory of triangular shape.

$$x_{n+1} = \begin{cases} \alpha x_n & \text{for } x_n < 0.5\\ \alpha (1-x_n) & \text{for } 0.5 \le x_n \end{cases}$$
(3)

Equation of Tent map is expressed as equation(3). Equation of Tent map uses existing output value as current input value, and it is indicated as figure 3 when initial value is 0.1 and parameter alpha is 1.9999.

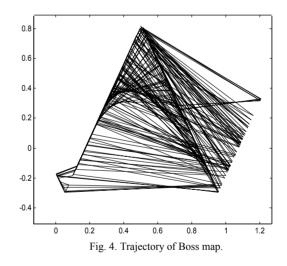


Figure 4 shows trajectory of Boss map that proposed a novel chaos map in order to improve the BER performance. The x-axis and the y-axis of Boss map mean x_n and y_n unlike the Tent map, it draws trajectory like pyramid shape.

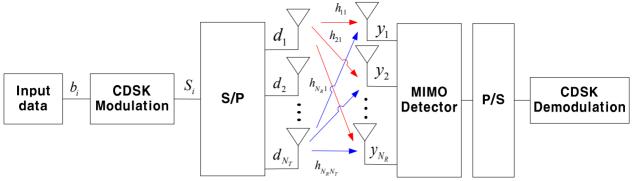


Fig. 5. Block diagram of CDSK system with 2x2 MIMO.

$$x_{n+1} = \alpha |0.45 - |0.503 - x_n||$$

$$y_{n+1} = x_n - 0.3$$
(4)

...

Equation of Boss map is expressed as equation(4). Equation form of Boss map is similar to Tent map because Boss map was proposed by transforming from Tent map. And, trajectory of Boss map is indicated as figure 4 when initial value is 0.1 and parameter alpha is 2.5.

C. CDSK System applied MIMO Technique

In order to apply the MIMO system to other systems, MIMO detection algorithm is necessary. Types of MIMO detection algorithm are various, but we apply Zero Forcing and MMSE in this paper. Also, performance evaluation of each algorithm is required because BER performance is changed according to types of MIMO detection algorithm.

Figure 5 shows the block diagram of CDSK system that applied 2x2 MIMO system. In MIMO environment, received signal includes transmitted signal from the others antenna except desired signal. So, MIMO detection algorithm is used in order to detach this signal. Afterward, information bits are recovered through CDSK receiver. We assume that the number of transmitter and receiver antenna is 2.

$$y_{1} = h_{1,1}d_{1} + h_{1,2}d_{2} + n_{1}$$

$$y_{2} = h_{2,1}d_{1} + h_{2,2}d_{2} + n_{2}$$

$$\begin{bmatrix} y_{1} \\ y_{2} \end{bmatrix} = \begin{bmatrix} h_{1,1} & h_{1,2} \\ h_{2,1} & h_{2,2} \end{bmatrix} \begin{bmatrix} d_{1} \\ d_{2} \end{bmatrix} + \begin{bmatrix} n_{1} \\ n_{2} \end{bmatrix}$$
(5)

Equation(5) indicates first received signal. y_1 and y_2 indicate received symbols to first and second antenna. And, these are expressed as matrix like equation(5) for convenience. Only transmitted signal from first transmitted antenna has to be received to first received antenna. But, looking at the equation(5), it is able to know that the transmitted signal form the others antenna was added to desired signal. By these reason, MIMO detection algorithm uses in receive part.

$$y = Hd + n$$

$$W = (H^{H}H)^{-1}H^{H}$$
(6)

$$Wy = (H^{H}H)^{-1}H^{H}(Hd+n)$$

= d + (H^{H}H)^{-1}H^{H}n (7)

Equation(6) is expressed the pseudo Inverse that is content with WH=I in order to find transmitted signal x. Received signal y is indicated that transmitted signal x is multiplied by channel H and is added noise n. So, transmitted signal x is detached by multiplying the pseudo Inverse W and the received signal y like equation(7), this method means Zero Forcing.

$$E\{[Wy-d][Wy-d]^{H}\}]$$

$$W = (H^{H}H + N_{0}I)^{-1}H^{H}$$
(8)

Equation(8) is expressed the pseudo inverse of MMSE. Pseudo inverse of MMSE is similar to Zero Forcing, but N_0I term exist in MMSE. In the case of the Zero Forcing, Pseudo Inverse is found by using estimation matrix equation. However, pseudo Inverse of MMSE is found by considering not only estimation matrix equation but also noise. Therefore, performance of MMSE is superior to Zero Forcing.

III. Performance Evaluation

In this paper, in Rayleigh fading channel, BER performances of CDSK system that is applied 2x2 MIMO with Zero Forcing and MMSE evaluate. Also, spreading factor is decided on 100, type of chaos map is decided on Tent map and Boss.

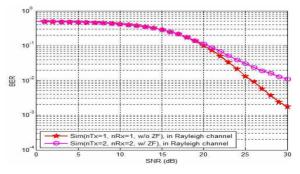


Fig. 6. BER performance of CDSK for 2x2 MIMO with Zero Forcing.

In Rayleigh channel, Figure 6 shows BER performance of CDSK system that is applied 2x2 MIMO with Zero Forcing. Looking at the figure 6, BER performance of CDSK system that is applied 2x2 MIMO with Zero Forcing correspond to BER performance of 1x1 CDSK system until SNR(Signal-to-Noise Ratio) is 20dB. However, this BER performance is evaluated badly than 1x1 CDSK system, when SNR is above 20dB. If pseudo inverse of Zero Forcing is multiplied to received signal, noise term like equation(7) become bigger than noise term of 1x1 CDSK system when SNR is above 20dB. So, BER performance is evaluated badly until SNR is 20dB.

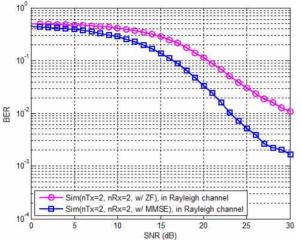


Fig. 7. BER performance of CDSK system for 2x2 MIMO with MMSE.

Figure 7 shows BER performance of CDSK system that is applied 2x2 MIMO with MMSE and Zero Forcing, and this figure compares Zero Forcing and MMSE. As MIMO detection algorithm, if MMSE is used, BER performance is superior to Zero Forcing. Because pseudo inverse of MMSE is considered not only estimation matrix equation but also noise term, and minimizes errors.

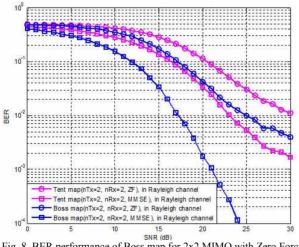


Fig. 8. BER performance of Boss map for 2x2 MIMO with Zero Forcing and MMSE.

Figure 8 shows BER performance of Boss map that is applied 2x2 MIMO with Zero Forcing and MMSE as MIMO

detection algorithm. If MMSE is applied to CDSK system using Boss map, BER performance is superior to BER performance that is applied Zero Forcing. And, BER performance of Boss map is improved than Tent map is used.

IV. Conclusion

In this paper, in Rayleigh fading channel, BER performances of 2x2 MIMO CDSK system applying MIMO detection algorithm like Zero Forcing and MMSE is evaluated. Chaos communication system has many transmitted symbols, because information signal is spread due to the characteristic of chaos map. This paper we know that in 2x2 MIMO environment this symbol is able to detach through Zero forcing and MMSE. If Zero Forcing is used as MIMO detection algorithm, BER performance of 2x2 MIMO CDSK system applying Zero Forcing correspond to BER performance of 1x1 CDSK system, when SNR is low. But as SNR rises 2x2 MIMO CDSK system applying Zero Forcing performance gets worse than 1x1 CDSK system. And, if MMSE is used as MIMO detection algorithm, BER performance is very superior to Zero Forcing. When 2x2 MIMO CDSK system using BOSS map, applying MMSE CDSK system BER performance is superior than that is applying Zero Forcing. In conclusion, MMSE performance is better than Zero Forcing in chaos communication system because pseudo Inverse of MMSE is considering not only estimation matrix equation but also noise. And, in 2x2 MIMO environment, we can know that BER performance of Boss map is better than Tent map.

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