## Implementation of Dynamic HSV Adjusting Method for Lane Detection

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*Abstract*— We propose design and implementation of system that dynamically adjusts value range of HSV using a photo resistor. In autonomous driving, lane detection is operated by fixing the color range of the lane. However, the color range of the lane changes with environment (time variations, Illumination, etc.), so it is necessary to adjust the range. To do this, we create matrix that make correspond to measured illumination and HSV value. And we designed lane detection Including this matrix. Experiment was conducted in two ways: using headlight and not using it. Experimental results showed that lane was detected despite changing illumination levels.

*Keyword*— autonomous driving, lane detection, image process, sensor, auto-control



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