

Autoencoder based framework for drone RF signal classification and novelty detection

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Abstract—The increasing use of Unmanned Aerial Vehicles (UAVs) in modern civilian and military applications shows the urgency of having a robust drone detector that detects unseen drone RF signals. Ideally, the system can also classify known RF signals from known drones. This study aims to develop an incremental-learning framework which can classify the known RF signals, and further detect novel RF signals. We propose DEFEND: a Deep residual network-based autoEncoder FramEwork for known drone signal classification, Novelty Detection, and clustering. The known signal classification and novelty detection are performed in a semi-supervised and unsupervised manner, respectively. We used commercial drone RF signals to evaluate the performance of our framework. With our framework, we obtained 100% novelty detection accuracy at 1.04% False Alarm Rate (FAR) and 97.4% classification accuracy with only 10% labelled samples. Furthermore, we show that our framework outperforms the state-of-the-art (SoA) algorithms in terms of novelty detection performance.

Keyword—Deep neural networks, Unsupervised learning, UAV.



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Sofie Pollin (Senior Member, IEEE) received the Ph.D. degree (Hons.) from KU Leuven, Leuven, Belgium, in 2006. From 2006 to 2008, she continued her research on wireless communication, energy-efficient networks, cross-layer design, coexistence, and cognitive radio at UC Berkeley. In November 2008, she returned to IMEC, Leuven, to become a Principal Scientist in the Green Radio Team. Since 2012, she has been a tenure track Assistant Professor with the Department of Electrical Engineering, KU Leuven. Her research centers around networked systems that require networks that are ever more dense, heterogeneous, battery-powered, and spectrum constrained. Prof. Pollin is a fellow of the BAEF and Marie Curie.



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