Stabilized UAV Flight System Design for Structure Safety Inspection

Oh-hoon Cho*, Kyeong-jin Ban*, Eung-kon Kim*

* Department of Computer Science, Sunchon National University, {worldnet, multwave, kek}@sunchon.ac.kr Corresponding Author: Eung-kon Kim

Abstract— For the small air vehicle-based structure safety inspection, it is very important to collect the images without shaking and the data by manipulating the air vehicle, even though the inspector does not have professional experience. In this article, the method for the stabilized flight system design for the safety inspection of the small air vehicle-based structures.

Keyword— Quadcopter, Stabilization, UAV, Attitude controller, Optimized structure design, PWM, Autonomous Flight



Oh-hoon Cho

Oh-hoon Cho received the B.S. degree from Korea National Open University, Korea, in 2006, His M.S. degree from department of computer science, Sunchon National University, Korea, in 2013. His currently a Ph.D. student in computer science at the Sunchon National University, Korea, His current research interests include augmented reality, image processing, computer graphics.



Kyeong-Jin Ban

Kyeong-Jin Ban received the B.S., M.S., and Ph.D. degrees in computer science from Sunchon National University, Korea, in 2003, 2005, 2011, respectively. His current research interests include computer graphics, wireless sensor network, and augmented reality.



Eung-kon Kim

Eung-kon Kim received the B.S. degree from Chosun University, Gwangju,, Korea, in 1980, his M.S degree from department of electronics, Hanyang University, Seoul, Korea, in 1987, his Ph.D. degree from Chosun University, Gwangju, Korea, in 1992. His current research interests are computer vision, virtual/augmented reality, image processing, and computer graphics. Currently he is a professor in department of computer engineering, Sunchon National University, Korea.